

On the Emergence of Cross-Task Linearity in the Pretraining-Finetuning Paradigm

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Background: LMC

Linear Mode Connectivity (LMC)

Given dataset D and two modes θ_A, θ_B that $\text{Err}_D(\theta_A) = \text{Err}_D(\theta_B)^*$, two mode θ_A and θ_B satisfy the *linear mode connectivity* if

$$\forall \alpha \in [0, 1], \text{Err}_D(\alpha\theta_A + (1 - \alpha)\theta_B) \approx \text{Err}_D(\theta_A)$$

* $\text{Err}_D(\theta)$ denotes the classification error of the network $f(\theta; \cdot)$ on the dataset D .

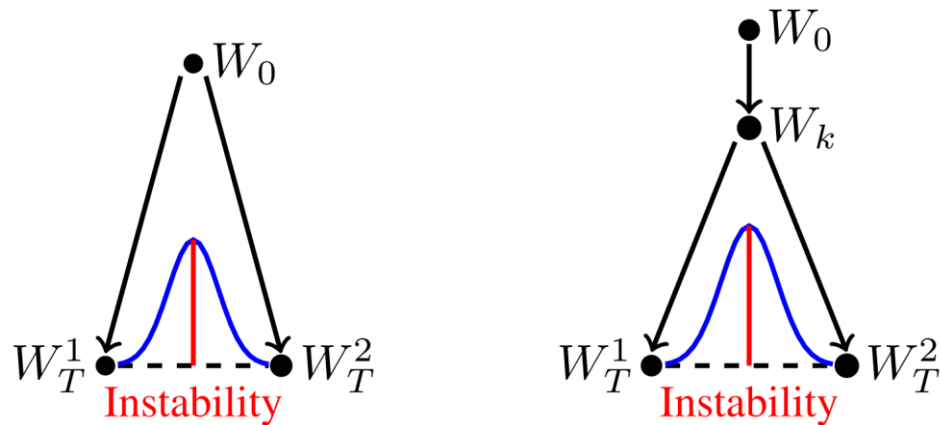


Fig. 1: Illustration of spawning method and LMC [1].

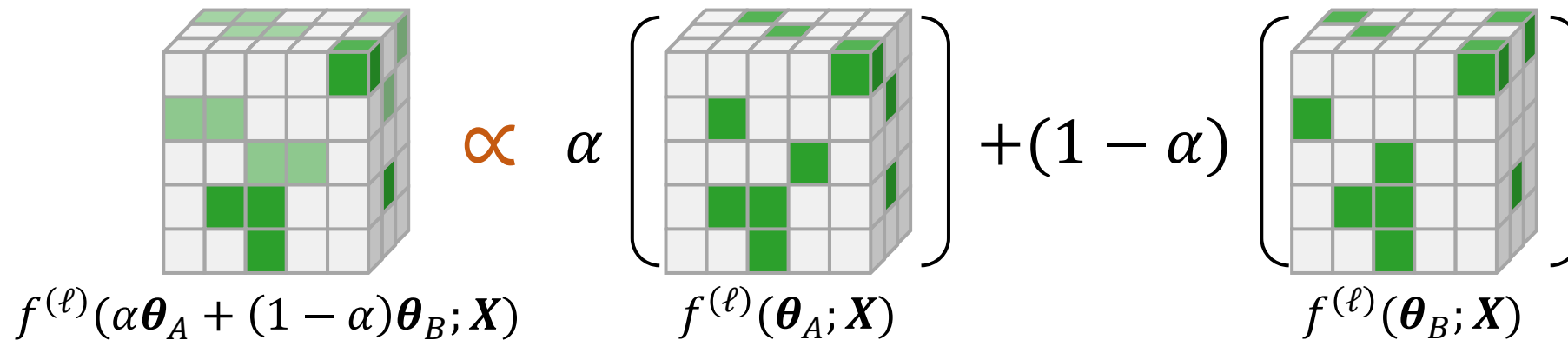
Frankle et al. [1] observed LMC for networks that are jointly trained for a short time before independent training (**spawning method**).

Background: LLFC

Layerwise Linear Feature Connectivity (LLFC)

Given dataset D and two modes θ_A, θ_B of an L -layer neural network f , the modes θ_A and θ_B are *layerwise linearly feature connected* if:

$$\forall \ell \in [L], \forall \alpha \in [0, 1], \exists c > 0, \text{ s.t. }, cf^{(\ell)}(\alpha\theta_A + (1 - \alpha)\theta_B) = \alpha f^{(\ell)}(\theta_A) + (1 - \alpha)f^{(\ell)}(\theta_B).$$



Background: LLFC connects to LMC

LLFC always co-occurs with LMC in practice

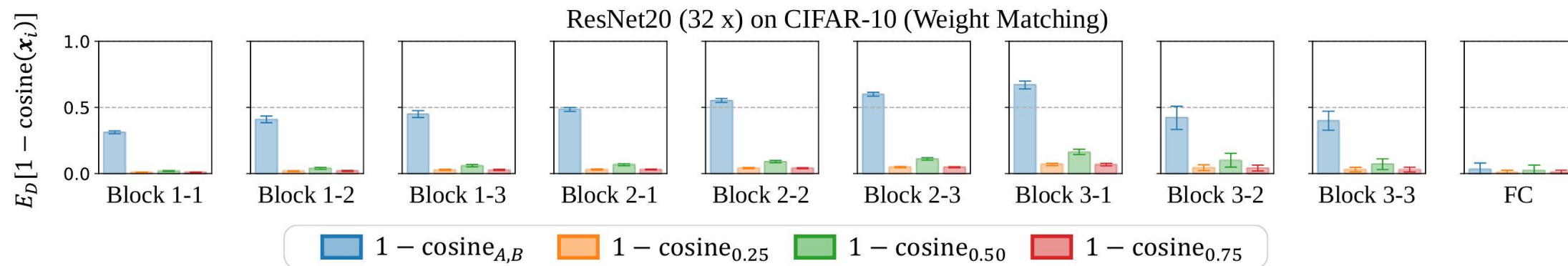


Fig. 2: Comparison of $E_D[1 - \text{cosine}_\alpha(\mathbf{x}_i)]^*$ and $E_D[1 - \text{cosine}_{A,B}(\mathbf{x}_i)]^*$, $\alpha \in \{.25, .5, .75\}$.

Lemma (LLFC implies LMC)

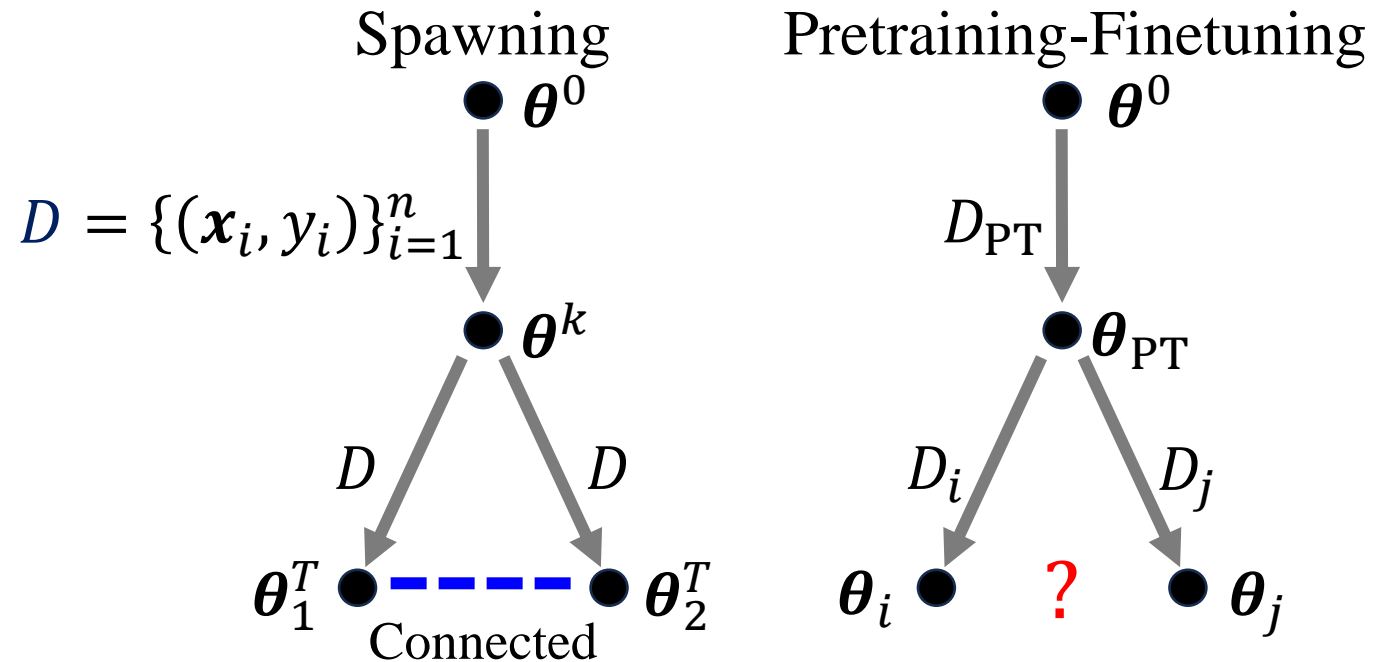
Two modes θ_A, θ_B satisfy LLFC over dataset D and $\max\{\text{Err}_D(\theta_A), \text{Err}_D(\theta_B)\} \leq \epsilon$, then

$$\forall \alpha \in [0, 1], \text{Err}_D(\alpha\theta_A + (1 - \alpha)\theta_B) \leq 2\epsilon.$$

* $\text{cosine}_\alpha(\mathbf{x}_i) = \cos\langle f^{(\ell)}(\alpha\theta_A + (1 - \alpha)\theta_B; \mathbf{x}_i), \alpha f^{(\ell)}(\theta_A; \mathbf{x}_i) + (1 - \alpha)f^{(\ell)}(\theta_B; \mathbf{x}_i) \rangle$ and $\text{cosine}_{A,B}(\mathbf{x}_i) = \cos\langle f^{(\ell)}(\theta_A; \mathbf{x}_i), f^{(\ell)}(\theta_B; \mathbf{x}_i) \rangle$

Pretraining-Finetuning Paradigm

Intuition: Finetuning shares similar training regime with the spawning method.



Are finetuned models linearly connected in loss landscape or feature space?

Cross-Task Linearity

LMC fails, LLFC holds.

Indeed, a stronger version of LLFC is observed, called *Cross-Task Linearity (CTL)*. Given a pair of finetuned models $(\theta_i, \theta_j) \in \Theta^2$ and downstream tasks D_i and D_j respectively, we say them satisfy CTL on $D_i \cup D_j$ if

$$\forall \ell \in [L], \forall \alpha \in [0, 1], s. t., f^{(\ell)}(\alpha\theta_i + (1 - \alpha)\theta_j) \approx \alpha f^{(\ell)}(\theta_i) + (1 - \alpha)f^{(\ell)}(\theta_j).$$

Conjecture (Transitivity of CTL.)

Given models $\theta_i, \theta_j, \theta_k$. We have (θ_i, θ_k) satisfy CTL if (θ_i, θ_j) and (θ_j, θ_k) satisfy CTL.

We can further apply CTL to explain *Model Soup* [6] and *Task Arithmetic* [6].

[5] Mitchell Wortsman, Gabriel Ilharco, Samir Yitzhak Gadre, Rebecca Roelofs, Raphael Gontijo-Lopes, Ari S. Morcos, Hongseok Namkoong, Ali Farhadi, Yair Carmon, Simon Kornblith, Ludwig Schmidt. Model soups: averaging weights of multiple fine-tuned models improves accuracy without increasing inference time.

[6] Gabriel Ilharco, Marco Tulio Ribeiro, Mitchell Wortsman, Suchin Gururangan, Ludwig Schmidt, Hannaneh Hajishirzi, Ali Farhadi. Editing Models with Task Arithmetic.

Insights into Model Averaging

Model Averaging (Uniform Model Soup)

Considering a set of models $\Theta = \{\boldsymbol{\theta}_i\}_k$ that started from $\boldsymbol{\theta}_{PT}$ and finetuned on the same task D_{FT} but with different hyperparameter configuration, model averaging is defined as

$$f\left(\frac{1}{k}\sum_{i=1}^k\boldsymbol{\theta}_i\right).$$

Connect model averaging and model ensemble

A finer-grained characterization of the linear correlation between model averaging and logits ensemble is observed.

$$f^{(\ell)}\left(\frac{1}{k}\sum_{i=1}^k\boldsymbol{\theta}_i\right) = \frac{1}{k}\sum_{i=1}^k f^{(\ell)}(\boldsymbol{\theta}_i), \forall \ell \in [L].$$

Insights into Model Averaging

Theorem (CTL generalizes to multiple models.)

Given dataset D and a set of models Θ where each pair of models $(\theta_i, \theta_j) \in \Theta^2$ satisfies CTL on D , assuming transitivity of CTL, then for any $\{\theta_i\}_{i=1}^k \in \Theta$ and $\{\alpha_i\}_{i=1}^k \in [0,1]$, subject to the constraint that $\sum_{i=1}^k \alpha_i = 1$,

$$f^{(\ell)}\left(\sum_{i=1}^n \alpha_i \theta_i\right) = \sum_{i=1}^n \alpha_i f^{(\ell)}(\theta_i), \forall \ell \in [L].$$

The connection between model averaging and ensemble can be viewed as a generalization of CTL to the case of multiple models in the pretraining-finetuning paradigm.

Insights into Task Arithmetic

Task Arithmetic

Considering a set of modes $\Theta = \{\boldsymbol{\theta}_i\}_k$ that started from $\boldsymbol{\theta}_{PT}$ but finetuned on different tasks $\{D_i\}_k$, task vector $\{\tau_i\}_k$ is defined as $\tau_i = \boldsymbol{\theta}_i - \boldsymbol{\theta}_{PT}$. Arithmetic operations can be applied to task vectors to construct τ_{new} and τ_{new} can be applied to $\boldsymbol{\theta}_{PT}$, i.e.,

$$f(\boldsymbol{\theta}_{PT} + \lambda\tau_{new}).$$

CTL explains learning via addition.

$f(\boldsymbol{\theta}_{PT} + \lambda(\tau_i + \tau_j))$ demonstrate abilities on both D_i and D_j . As CTL holds (verified empirically), $\forall \ell \in [L]$,

$$f^{(\ell)}(\boldsymbol{\theta}_{PT} + \lambda(\tau_i + \tau_j)) \approx \frac{1}{2}f^{(\ell)}(\boldsymbol{\theta}_{PT} + 2\lambda\tau_i) + \frac{1}{2}f^{(\ell)}(\boldsymbol{\theta}_{PT} + 2\lambda\tau_j).$$

Addition over parameter space can be transformed to feature space.

Insights into Task Arithmetic

CTL explains forgetting via negation.

$f(\boldsymbol{\theta}_{PT} - \lambda\tau_i)$ loses ability on D_i while retains performance elsewhere. As CTL holds (verified empirically),

$$f^{(\ell)}(\boldsymbol{\theta}_{PT}) \approx \frac{1}{2}f^{(\ell)}(\boldsymbol{\theta}_{PT} - \lambda\tau_i) + \frac{1}{2}f^{(\ell)}(\boldsymbol{\theta}_{PT} + \lambda\tau_j).$$

We rewrite it as

$$f^{(\ell)}(\boldsymbol{\theta}_{PT} - \lambda\tau_i) \approx f^{(\ell)}(\boldsymbol{\theta}_{PT}) - \Delta^{(\ell)}(\lambda\tau_i),$$

where $\Delta^{(\ell)}(\lambda\tau_i) = f^{(\ell)}(\boldsymbol{\theta}_{PT} + \lambda\tau_j) - f^{(\ell)}(\boldsymbol{\theta}_{PT})$. Intuitively, $\Delta^{(\ell)}(\lambda\tau_i)$ encode the information specific to task D_i .

Negation over parameter space can be transformed to feature space.

Unveiling the Root Cause of CTL

Factors Contributing to CTL (Highlight the role of pretraining).

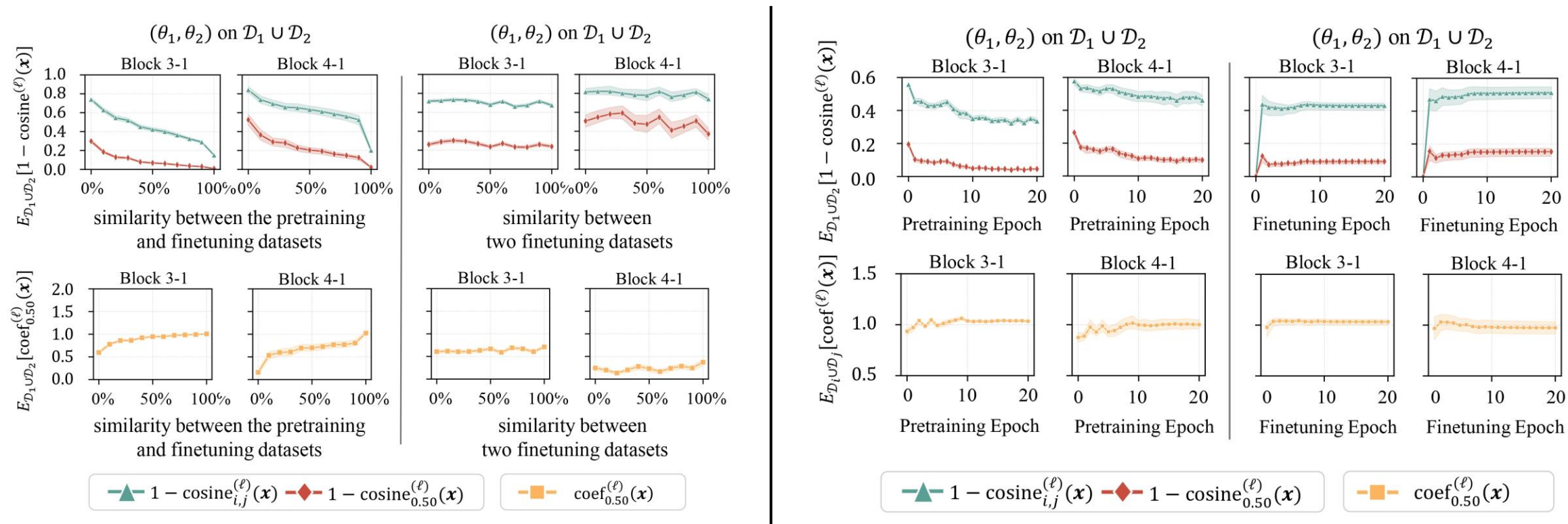


Fig. 3: The impact of the **task similarity (left) / number of pretraining and finetuning epochs (right)** on the emergence of CTL.

Unveiling the Root Cause of CTL

Theorem (The Emergence of CTL.)

Suppose $f(\boldsymbol{\theta}): R^p \mapsto R$ is third-differentiable function in an open convex set Θ and its Hessian norm at $\boldsymbol{\theta}_0$ is bounded by $\lambda_{min} \leq |\nabla^2 f(\boldsymbol{\theta}_0)| \leq \lambda_{max}$, then

$$|f(\alpha\boldsymbol{\theta}_i + (1 - \alpha)\boldsymbol{\theta}_j) - \alpha f(\boldsymbol{\theta}_i) - (1 - \alpha)f(\boldsymbol{\theta}_j)| \leq \frac{\alpha(1 - \alpha)\lambda_{max}}{2} \|\boldsymbol{\theta}_i - \boldsymbol{\theta}_j\|^2 + \epsilon,$$

Where $\epsilon = O(\max(\|\alpha\boldsymbol{\theta}_i + (1 - \alpha)\boldsymbol{\theta}_j - \boldsymbol{\theta}_0\|^3, \alpha\|\boldsymbol{\theta}_i - \boldsymbol{\theta}_0\|^3, (1 - \alpha)\|\boldsymbol{\theta}_j - \boldsymbol{\theta}_0\|^3))$ is the higher order term.

Remarks:

- *The emergence of CTL is related to the flatness of the function landscape and distance between two finetuned models.*
- *Instead of linearizing models, we provide a more realistic setting.*

Thank you!

Q&A